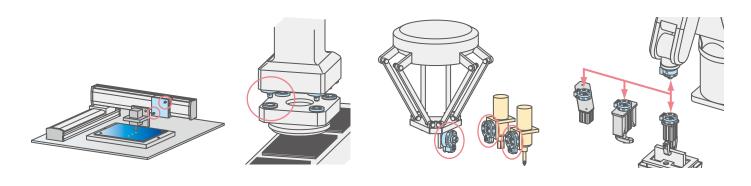
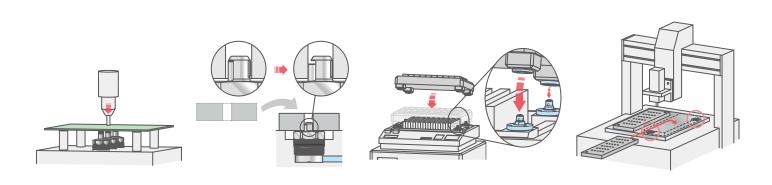
FA · Robotic Automation Products

# **Application Examples**

For Automotive • Semiconductor • LCD Panel Electronics • Precision Equipment Industries



## **More Automation Solutions**





#### Product Line-Up



Clamp Coupler

#### **Robotic Hand Changer**

Model SWR

High Accuracy • High Rigidity • Long Life No Backlash

Locating Repeatability:  $3 \mu m$  Compact and Easy to Use

Allowable Load (at Pneumatic Pressure 0.5MPa): 3kg / 7kg / 12kg / 25kg / 50kg / 75kg / 120kg





Clamp

#### Pneumatic Location Clamp

Model SWT

#### Locates and Clamps Simultaneously

Locating Repeatability: 3  $\mu$  m

Clamping Force (at Pneumatic Pressure 0.5MPa): 0.8kN / 1.5kN / 2.3kN / 3.3kN / 5.1kN





Clamp

Bolt Size: M4/M5/M6/M8/M10/M12/M16

#### **Screw Locator**

Model VXF

Simple Manual Setup High Accuracy Locating of Pallets/Plates

Locating Repeatability: 3  $\mu$  m Most Suitable for Pallets and Equipments Requiring High Accuracy Locating

M4/M5 sizes are added to the line-up! Most Suitable for Locating Small Plates





### **Expansion Locating Pin** Smaller Diameter Model

Model VRA/VRC





#### Pneumatic Expansion Locating Pin

Model WM

Zero Clearance with High Accuracy Locating Pin Locating Repeatability:  $3 \mu$  m

Workpiece Hole Diameter:  $\phi 8 / \phi 9 / \phi 10 / \phi 12 / \phi 13 / \phi 15 / \phi 16 / \phi 18 / \phi 20$ 



#### Manual Expansion Locating Pin

Model VX

Zero Clearance with High Accuracy Manual Locating Pin

Locating Repeatability: 5  $\mu$  m

Workpiece Hole Diameter:  $\phi 8 / \phi 10 / \phi 12 / \phi 16 / \phi 20$ 



#### Robotic Hand

Model WPH/WPP/WPO





Parallel Robotic Hand Gripper Model WPH



Three-Jaw Chuck Model WPP



Model WPO

Clamp

### High-Power Pneumatic Clamp

Model WHE/WCE/SWE





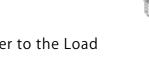


Higher Clamping Force and Holding Force with Mechanical Lock and Pneumatic Pressure Clamping Force which Withstands the Load with Holding Force does not Distort the Workpiece.



#### Auto Backup Pin

Model WDC



Prevents Chattering and Distortion Counter to the Load Pin Touches Workpiece Softly and Stops to Provide Support



#### Support

#### High-Power Pneumatic Work Support

Model WNC



Firmly Supports the Workpiece and Prevents Chattering/Distortion The World's First Collet-Style Work Support with Pressure Range of 0.25~0.7MPa.



#### **Auto Coupler**

Model JVA/JVB JVC/JVD JVE/JVF











#### Compact Coupler to Connect Hydraulic/Pneumatic Circuits Connection Stroke: 1mm Commonly Used with Screw Locator and Pneumatic Location Clamp

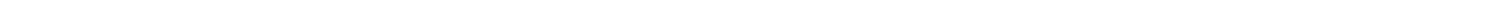
#### Air Sequence Valve

 $Model\ BWD$ 



Actuates Multiple Air Actuators in Sequence Without Electricity.

Delay Time: 1~10sec Most Suitable for Electricity-Free Environments



#### Kosmek works to meet the needs of every customer, developing and producing innovative products.

http://www.kosmek.co.jp

We have various types of hydraulic and pneumatic products. Please let us know your requirements, and we will make it happen.

For further information of each product, please refer to "FA · Robotic Automation Products Complete Catalog". Please contact us or request it from our website.

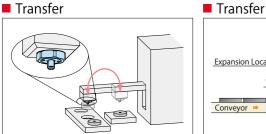


FA · Robotic Automation Products Complete Catalog Catalog No.FA0020□-□-GB





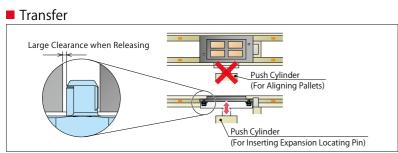
Soldering, Sealing ■ Welding



**Expansion Locating Pin** 

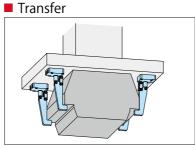
Expands to hold the workpiece hole. Clamps the tray hole and transfers it to the storing shelf. For Pick-and-Place of Table Robots

Model

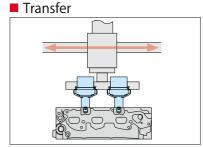


Expansion locating pin allows for easy pallet loading/unloading. It prevents transfer error of conveyors.

Model

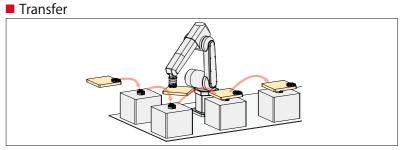


Prevents workpiece from falling with holding force even at 0MPa.



Minimize the Transfer Equipment by clamping workpiece hole.

Model



Robotic Hand Changers mounted to the pallets. It enables not only tool change, but also pallet transfer.

Model SWR SWT WVS



High accuracy locating of Robotic Hand Changer reduces fluctuation of press machine transfer arm and prevents errors.

Model SWR ■ Transfer

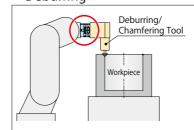
Long Stroke Robotic Hand allows for transferring various kinds of workpieces.

Model

Deburring

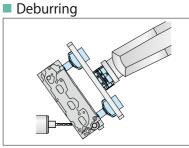






High accuracy robotic tool changer improves machining accuracy.

SWR Model



Clamps the workpiece by holding its holes. Clamps the workpiece with holding force. No Interference, Smooth Deburring

Model

Sealing

SWR SWE

Scratches on the workpiece will be minimized.

Welding

Model WHE WCE

Soldering



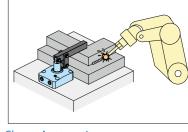
high accuracy robotic tool changer.

Model

SWR



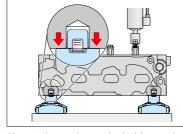
Soldering accuracy will be improved by High accuracy robotic tool changer improves sealing accuracy.



**Clamp Automation** \* Spatter measurement is required.

WHA WCA

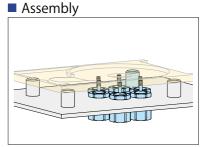




Assembly

Clamps the workpiece by holding its holes. Supports press fitting during HDD Smooth Assembly with No Interferes

Model SWE



assembly, preventing deformation.

Model WDC

> No Backup Load

Assembly

Supports thin-walled part preventing deformation and cracking.

With Backup

Load

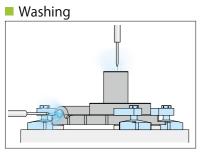
Model WDC WNC

# **Application Examples**



Assembly

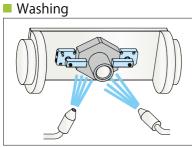
Model



Clamps the workpiece with holding force. Scratches on the workpiece will be minimized.

Model





Washing Machine Automation with **Automatic Clamps** 

Model WHA WCA

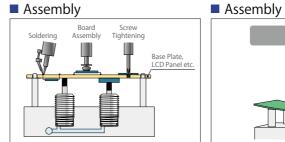
Assembly

High accuracy locating facilitates precision work.







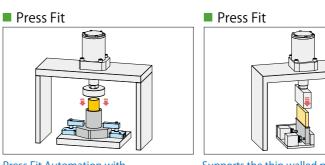


Supports the bottom of the circuit board. Supports and backups the workpiece from the bottom Prevents backlash during board assembly. preventing deformation caused by various kinds of loads.

Model



WDC WNC



Press Fit Automation with **Automatic Clamps** 

Model

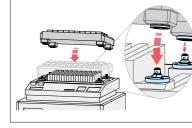
Model WDC





deformation caused by press fit.

Model WNC



Supports the thin walled part, preventing Improves accuracy of the semiconductor test device. Locates cassette with high accuracy.

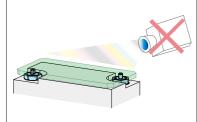
> Holding Force Thrust Force

> > 6

Model SWT WVS

Test





Cost Reduction in Adjustment Equipment Improves locating accuracy during with High Accuracy Locating

Model

pallet change.

Assembly

Without backlash, robotic tool changer facilitates screw tightening and reduces defects.

Model SWR

Test Test

Engine Test Device Tool Change Standardization of Test Device

Model

SWT SWR

with clamping force and holding force.

Model

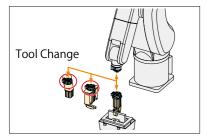
WHE WCE

Securely holds the pressure container for leak test



## **Application Examples**

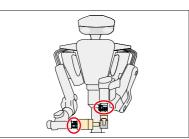
#### **Robot Examples**



**Articulated Robot** Standardized Tool Change

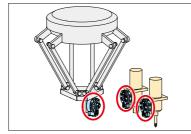
Model





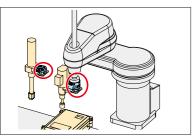
**Humanoid Robot** End of Arm Tool Change





Parallel Link Robot Screw Tightening Tool Change

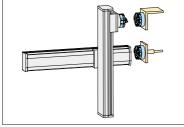




Scara Robot **Nut Runner Tool Change** 

Model

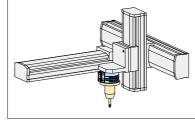




2-Axis Cartesian Coordinate Robot Test Device Tool Change

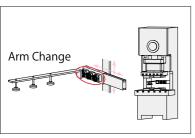
Model





3-Axis Cartesian Coordinate Robot **Tool Change** 

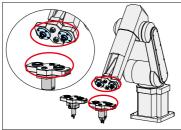




Press Machine Transfer Arm Change

Model





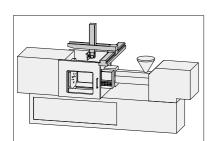
Design various kinds of robotic hands. Unloading Machine Tool Pallets/Workpieces





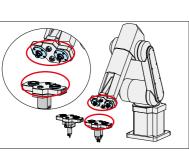






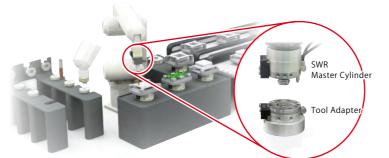
Injection Molding Machine **Take-Out Robot** 





**Articulated Robot** 

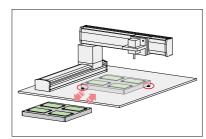




High-precision Robotic Hand Changer enables multiple functions of robots and setup time reduction. It enhances the productivity of automated production line.

## **Application Examples**

#### **Setup Improvement Examples**



Cartesian Coordinate Robot **High-Accuracy Pallet Setup** 







Cartesian Coordinate Robot High-Accuracy Light Tool Setup



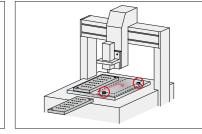


Table Robot High-Accuracy Pallet Setup



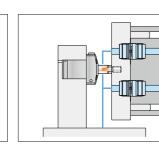












**During Pallet Change** Locates with VXF, connects circuits with JVA/B



Semiconductor Test Device

**High-Accuracy Cassette Setup** 

SWT WVS

Ink-Jet Device

**Head Change** 

Model

Model



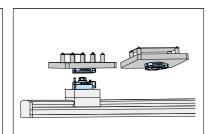




Model JV



Circuit Connection Automation



Single Axis Robot Pallet Change

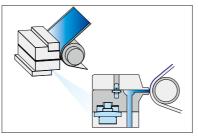
Production Line of LCD Panels





Model

SWR



Die Coater Setup During Washing











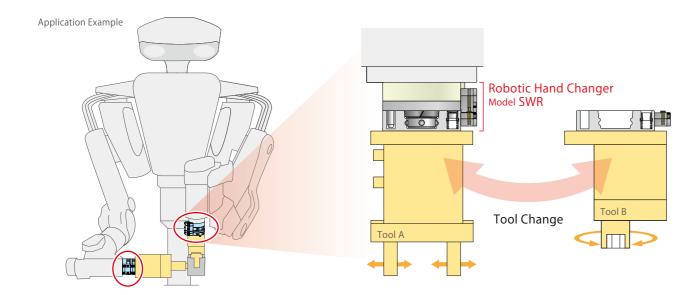
Coating and Coater Head



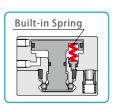


Kosmek Robotic Hand Changer is used for

### **Humanoid Robot Tool Change**



### 6 Reasons to Choose KOSMEK



#### Safe • Anti-Falling of Tool

Even without air supply, built-in spring maintains mating condition which prevents tool from falling.



#### **Light Weight • Compact**

Suitable for robotic hands which are near the weight limit.

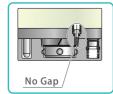
Light Weight yet Large Load Capacity!!

It shows the weight of SWR0030 without the electrode.



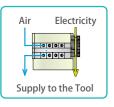
#### **Enhances Work Efficiency**

No backlash on mating part. Highly reliable electrode prevents momentary stop caused by communication error.



#### No Backlash on Mating Part

No backlash (clearance) on mating part and most suitable for high load and high accuracy operation.



#### Connect Air/Electricity to the Tool

By air port and electrode, it is able to connect air and electricity to the tool side. Electrode is selectable from solder terminal, D-SUB connector and power transmission connector.

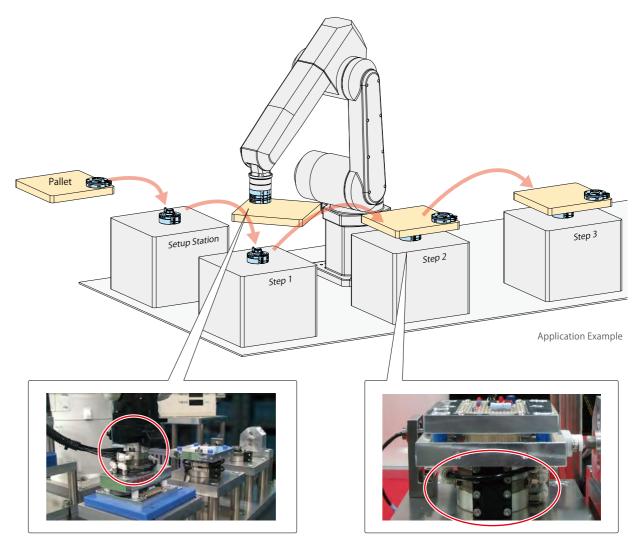


#### **Prevents Fluctuation**

Locating repeatability of tool change is 0.003mm. Reduces the fluctuation of hand tool and conducts high accuracy operation.

Kosmek Robotic Hand Changer is used for both

### Transfer Robots and Pallet Locating



For Transfer Robot

For Locating Pallets



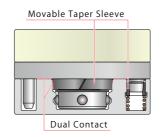
#### Locating Repeatability: within 3 $\mu$ m

No backlash on mating part with the dual surface contact of movable taper sleeve.

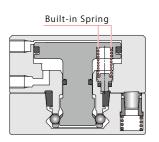


#### **Pallet Fall Prevention**

Mechanical locking system maintains mating condition with built-in spring.



High Accuracy Locating with Dual Contact



Built-in spring maintains the locked state.

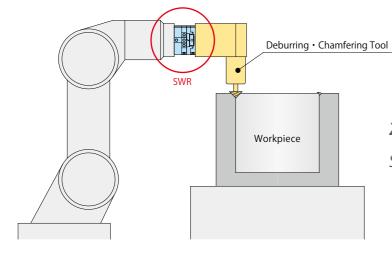




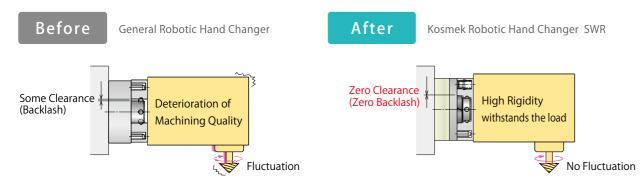


Kosmek Robotic Hand Changer is used for

## **Deburring • Chamfering Robots** for **Aircraft Engine Components**



Zero Backlash Suitable for Heavy Load Work



Locating Repeatability of Tool Change:  $3 \mu m$ 



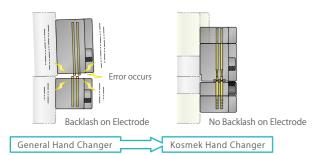
#### **Enhances Work Efficiency**

No backlash on mating part is due to the dual surface mechanism with movable taper sleeve.



#### Supplies Air/Electricity to the Tool

Air and electrical connections to the pallet available with the air port and electrode.



Kosmek hand changer has no backlash on electrode with dual surface contact.

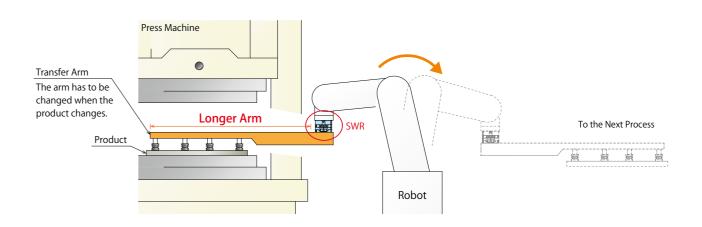
11



Air blow function is for cleaning the taper reference surface and seat surface.

Kosmek Robotic Hand Changer is used for

### **Transfer Arm Change of Press Machine Automatic Line**



Kosmek robotic hand changer minimizes fluctuation of the longer arm.



After

Kosmek Robotic Hand Changer SWR

With high locating accuracy (3  $\mu$  m), fluctuation of the arm

end is minimal. Since there is no clearance or backlash, the

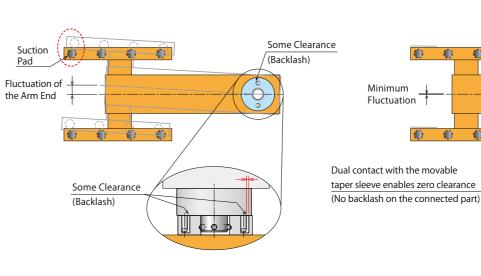
moment of robot movement does not affect attaching and

detaching products. Prevent errors on attaching and

detaching with high accuracy locating.

No Clearance

(No Backlash)



With low locating accuracy, fluctuation of the arm end becomes larger. Clearance on the hand changing part may result in gap due to the moment of robot movement. When suction pad is off-position, the pad may not adsorb products, or it cannot place products properly after transferring them.

\* Drawings do not show actual dimensions.

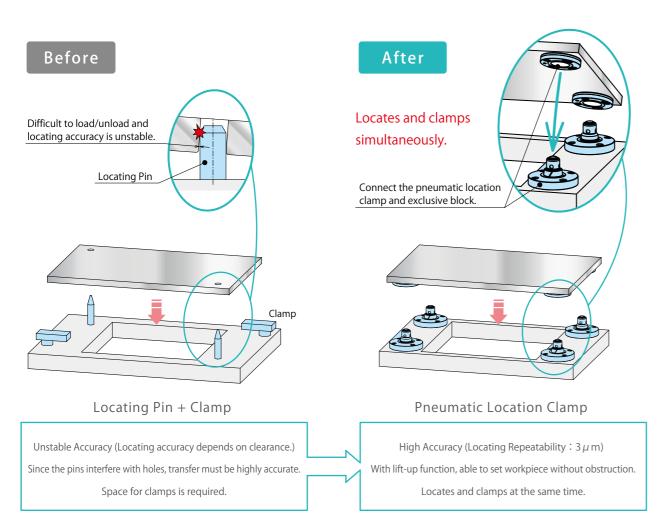




Pneumatic Location Clamp is used for

### **Locating and Clamping of Pallet/Tray Change**

Model SWT

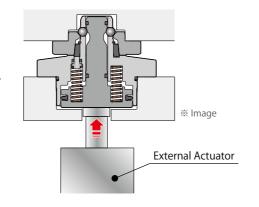


#### Application Example for Vacuum Facility

We are able to accomodate a fixture that does not supply air in a vacuum environment with SWTY which has the same function as SWT. \*\*Please contact us for use in this environment.

#### Example

Release with an external actuator (prepared by customer) (Release action by lifting up a piston from the bottom of SWTY), and lock with spring. SWTY on the fixture operates without air supply.



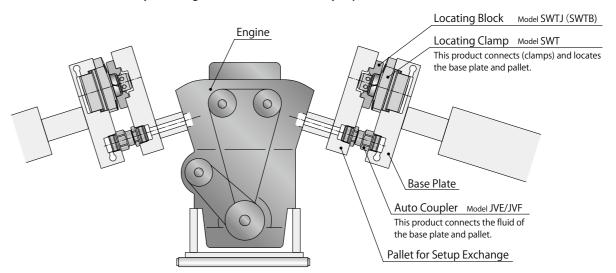
Pneumatic Location Clamp and Auto Coupler are used for

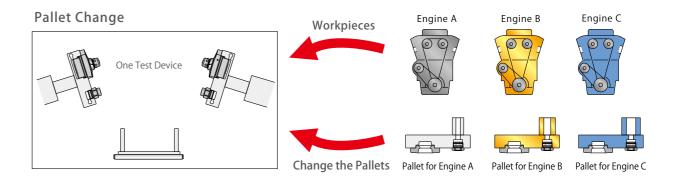


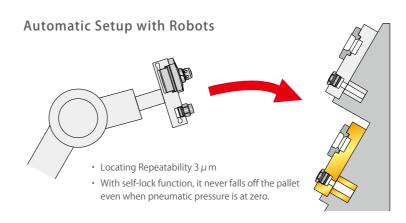
### **Automatic Setup Change of Engine Cold Test Device**

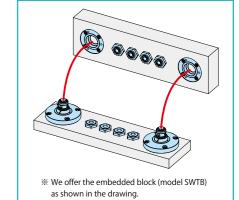
In an engine cold test (engine function test in non-fired state), **every time an engine model changes, testing device had to be exchanged** due to **the design of the testing device**.

Applying pneumatic location clamp to a part (the joint part of an engine and testing device.) of testing device enables the **automatic setup exchange (time reduction in setup)** by the robot.

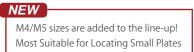












Screw Locator is used for



# High-Accuracy Locating for Pallet/Tray Change



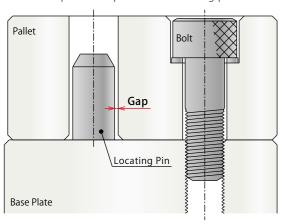
Screw Locator performs high-accuracy locating simply by fastening the bolts.

Before Genera

General Locating Pin

# Mechanical pins have **clearance** creating unreliable accuracy and repeatability.

Less accuracy due to backlash
Space is required for mounting pins.

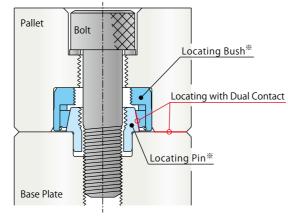


### After

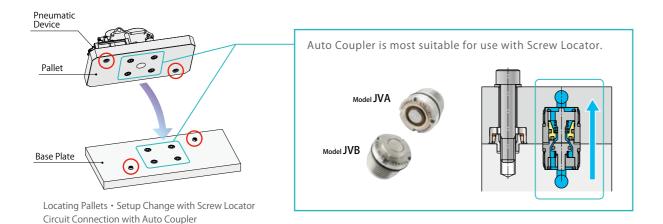
Screw Locator

# With Dual Contact of Screw Locator Locating Repeatability is 3 $\mu$ m

High locating accuracy makes less defective parts. More Compact and Space-Saving

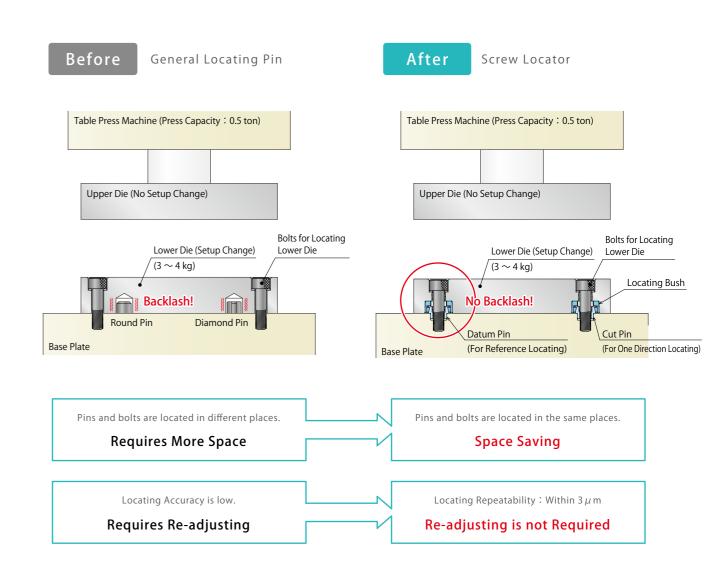


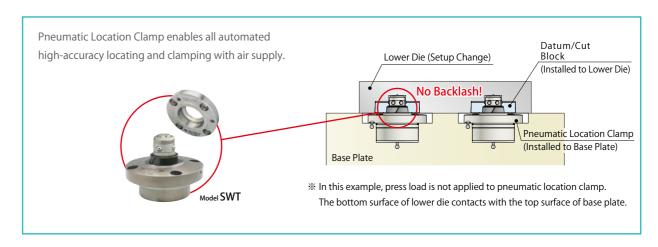
\* Screw locator consists of the locating pin and locating bush.



Screw Locator is used for

# High-Accuracy Locating of Lower Die of Table Press Machine



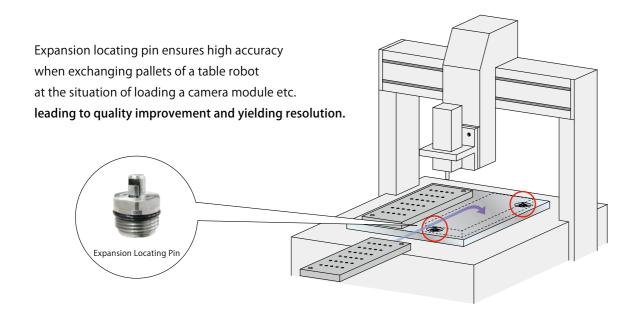


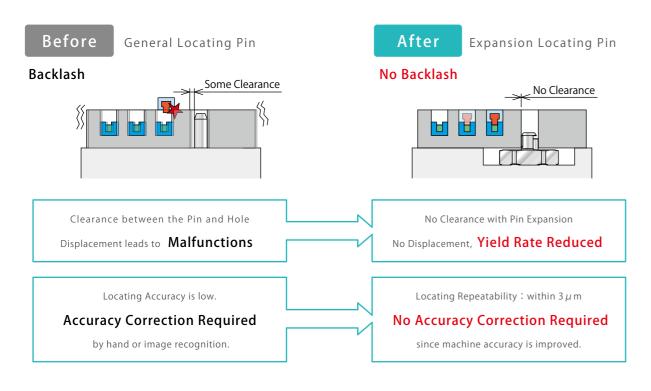




Expansion Locating Pin is used for

# High Accuracy Locating for Pallet Change of Table Robot (Equipped with Camera Module Lens etc.)





#### Quality Improvement • Cost Reduction

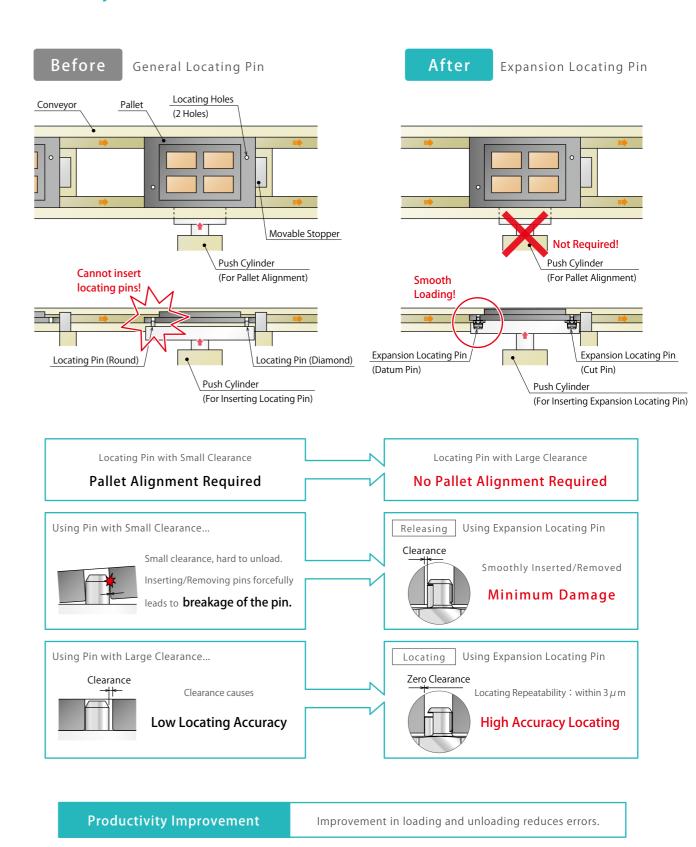
Accuracy improvement of locating pin leads to high accuracy operation and cost reduction in adjustment equipment.



Improvement in Locating Accuracy of the Machine

Expansion Locating Pin is used for

# Automatic Loading • High Accuracy Locating of Pallets with Conveyor Transfer (Assembly Process for Smart Phone Components)



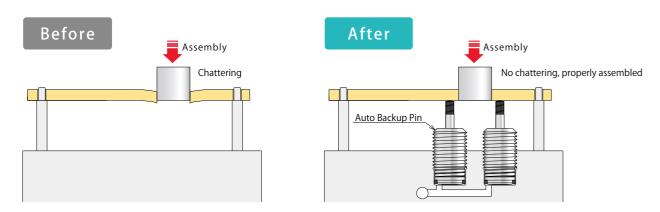




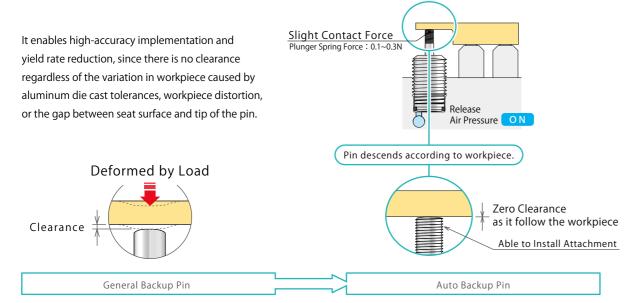
Auto Backup Pin is used for

### **Chattering Prevention of HDD Parts Assembly**

Parts Assembly Prevents chattering caused by assembly (press fit) and assembly defects. Auto Backup Pin



Auto backup pin contacts workpiece softly and holds it instantly (3N). No clearance between the workpiece and pin since it follows the height of workpiece.

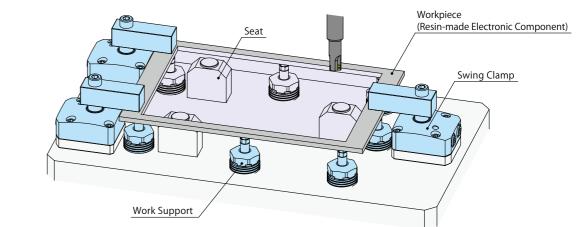


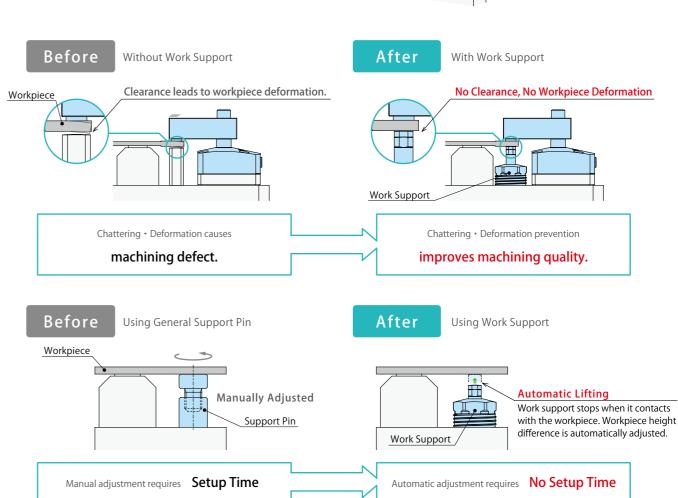
High-Power Pneumatic Work Support is used for

## Chattering/Deformation Prevention for Finishing Process of Resin-made Component



High-quality resin-made electronic component requires machining for finishing process. Kosmek work support prevents deformation or chattering on thin components and enables high quality machining. It also provides shorter setup time.





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Model WDC

Model WCE

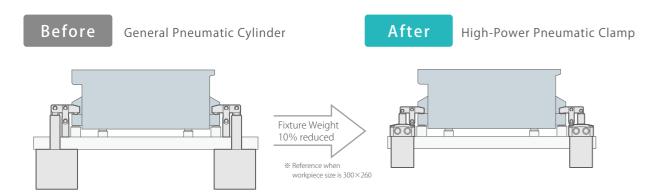




Model WHE

High-Power Pneumatic Clamp is used for

### **Fixtures with Limited Space**



High-power pneumatic clamp has compact body yet **exerts equivalent clamping force** to our conventional model. By reducing the weight of fixture, the load to equipment will be minimized.



#### Strong Clamping Force with Mechanical Lock

Exerts approximately 3 times higher clamping force than the same size comparison pneumatic cylinder.



#### **Holding Force**

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Holding force is the force that endures reaction force (load), not the force that presses a workpiece.

The high holding force enables heavy load machining and high accurate machining.

 $\,$  Comparison of Cylinders with Piston Diameter  $\,\phi$  40 (Air Pressure 0.4MPa, Lever Length 60mm)

### **Company Profile**



KOSMEK LTD. Head Office

Company Name KOSMEK LTD.
Established May 1986
Capital ¥99,000,000

Sales 55 billion yen (period ended March 2014)

Chairman Keitaro Yonezawa President Tsutomu Shirakawa

Employee Count 220

Group Company KOSMEK LTD.

Business Fields

KOSMEK ENGINEERING LTD.

KOSMEK (USA) LTD. KOSMEK (CHINA) LTD.

Design, production and sales of precision products,

and hydraulic and pneumatic equipment

Customers Manufacturers of automobiles, industrial machinery,

semiconductors and electric appliances

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Tokyo Sales Office

Nagoya Sales Office

Fukuoka Sales Office

#### Product Line-up

We manufacture a wide range of clamping systems and components. Feel free to contact us.



#### ■ KOSMEK WORK CLAMPING SYSTEMS

#### MACHINE TOOL RELATED PRODUCTS

Our clamping system enables boltless automation making loading and unloading workpieces easier. The non-leak valve enables the use of hydraulic source and fixtures in a disconnected condition after locking (clamping action).



#### ■ QUICK DIE CHANGE SYSTEMS

#### FOR PRESS MACHINES

Kosmek Quick Die Change Systems are a cost effective way to improve the working environment, allow diversified and small-lot production, and reduce press down time. Available for a wide range of machines from large size transfer-presses to smaller high speed presses.



#### **QUICK MOLD CHANGE SYSTEMS**

#### FOR INJECTION MOLDING MACHINES

Automatic clamping systems have reduced mold change times and increased production efficiency for plastics manufacturers in a multitude of industries.

We offer a variety of clamping options including hydraulically powered clamps, pneumatic clamps with a force multiplying mechanism, and magnetic clamping systems.



#### ■ DIECAST CLAMPING SYSTEMS

#### FOR DIECAST MACHINES

Kosmek Diecast Clamping Systems (KDCS) enable stable die clamping for die casting and magnesium molding machines that are subjected to severe conditions caused by exposure to mold release agents and high temperature.

### **KOSMEK**

#### Harmony in Innovation

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- FOR FURTHER INFORMATION ON UNLISTED SPECIFICATIONS AND SIZES, PLEASE CALL US.
- SPECIFICATIONS IN THIS LEAFLET ARE SUBJECT TO CHANGE WITHOUT NOTICE.



#### http://www.kosmek.co.jp